

LAMPIRAN

Lampiran 1 Program

```
int kiri = 4;
int kiri2 = 5;
int kanan = 6;
int kanan2 = 7;

int pwm1 = 9;
int pwm2 = 10;

int sumbux;
int sumbuy;
int sumbu;

String accelero;
void setup() {
Serial.begin(9600);
Serial.setTimeout(5);

pinMode(kiri,OUTPUT);
pinMode(kiri2,OUTPUT);
pinMode(kanan,OUTPUT);
pinMode(kanan2,OUTPUT);
pinMode(pwm1,OUTPUT);
pinMode(pwm2,OUTPUT);

analogWrite(pwm1,200);
analogWrite(pwm2,200);
}

void loop() {
```

```

if (Serial.available() > 0)
{
    accelero = Serial.readString();
    //Serial.println(accelero);
    if(accelero.startsWith("X"))
    {
        accelero.replace("X", "");
        //Serial.print("X= ");
        //Serial.print(accelero);
        //Serial.print(" ");
        sumbux = accelero.toInt();
        //Serial.println(sumbux);
    }
    else if(accelero.startsWith("Y"))
    {
        accelero.replace("Y", "");
        //Serial.print("Y= ");
        //Serial.print(accelero);
        //Serial.println(" ");
        sumbuy = accelero.toInt();
        //Serial.println(sumbuy);
    }
    Serial.print("X=");
    Serial.print(sumbux);
    Serial.print(" Y=");
    Serial.println(sumbuy);

    delay(200);

    if ((sumbux > -15) && (sumbux < 15) && (sumbuy > -15) && (sumbuy < 15))
    {
        //maju
    }
}

```

```

Serial.println("MAJU");
digitalWrite(kiri, HIGH);
digitalWrite(kiri2, LOW);
digitalWrite(kanan, HIGH);
digitalWrite(kanan2, LOW);
}

if ((sumbux > -10) && (sumbux < 10) && (sumbuy > 20) && (sumbuy < 80))
{
//mundur

Serial.println("MUNDUR");
digitalWrite(kiri, LOW);
digitalWrite(kiri2, HIGH);
digitalWrite(kanan, LOW);
digitalWrite(kanan2, HIGH);
}

if ((sumbux > -10) && (sumbux < 10) && (sumbuy > -80) && (sumbuy < -20))
{
//stop

Serial.println("STOP");
digitalWrite(kiri, LOW);
digitalWrite(kiri2, LOW);
digitalWrite(kanan, LOW);
digitalWrite(kanan2, LOW);
}

sumbux = 0;
sumbuy = 0;
}

sumbux = 0;
sumbuy = 0;
}

```

Lampiran 2 Datasheet